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/* This program displays the Character Speed WPM on line 1 and Character
Clock Timing on line 2 of a 16 x 2
LCD display based on a HD44780 display controller. WA7RSO
Modified for Analog Input & Display of the Voltage on LCD Line 3
08/13/2013
*/
#include <LiquidCrystal.h> // alert compiler to include the lcd library

int RS = 8;           // Register Select on pin #4 of the LCD
int RW = 9;           // Read/Write on pin #5 of the LCD
int E = 10;          // Enable on pin #6 of the LCD

// initialize the library with the numbers of the Arduino pins used
LiquidCrystal lcd(RS, E, 4, 5, 6, 7); //defines the pins used from the
LCD to the Arduino (New Interface Board)

int rawNumber;

String CharSpeed20 = ("Char Speed-20WPM");
String CharClock20 = ("60 ms 16.7Hz Clk");
String InputVoltage;

void setup()           //required function
{
    // initialize serial communication at 9600 bits per second:
// Serial.begin(9600);      //see text
    pinMode(RW, OUTPUT);
    digitalWrite(RW, LOW);     // Allow "Writing" to the LCD

    lcd.begin(20,4);         //let the program know the size of the
display to be handled

    printspeed();            // calls the function to print the WPM
message
// printclock();           // calls the function to print the
first 16 characters of the message
}

void loop()             // Dummy Loop
{
// Read the analog input on pin #0
    int sensorValue = analogRead(A0);
// Convert the analog reading (which goes from 0 - 1023) to a voltage
(0 - 5V):
    float voltage = sensorValue * (5.0 / 1023.0);
// print out the value you read:
// Serial.println(voltage);
    lcd.setCursor(0,2);
// InputVoltage = Stringvoltage;
    lcd.print("Voltage: ");
    lcd.print(voltage);
    lcd.print("V");
    Clear4thLine();
}

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lcd.setCursor(0,3);
rawNumber = sensorValue;
lcd.print("Raw Value: ");
lcd.print(String(sensorValue));
delay(500);

}

void printspeed() // Show the Character Speed in WPM
{
    lcd.setCursor (0,0); // Set cursor at beginning of 1st
Row ("0")
    lcd.print(CharSpeed20); // print the WPM Character Speed
    Serial.println(CharSpeed20);
    lcd.setCursor(0,1); //sets cursor at the beginning of
the second line and then moves right
    lcd.print(CharClock20);
    Serial.println(CharClock20);
}

void Clear4thLine()
{
    lcd.setCursor(0,3);
    lcd.print(" ");
}
```